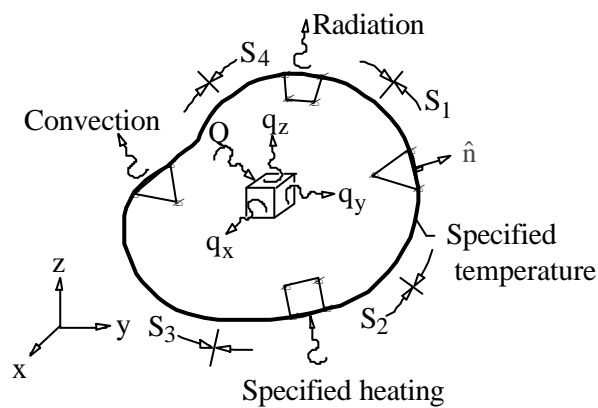


# FINITE ELEMENT METHOD FOR HEAT TRANSFER PROBLEMS

## HEAT TRANSFER PROBLEM



Governing differential equation,

$$-\frac{\partial}{\partial x} \left( \frac{\partial q_x}{\partial x} \right) + \frac{\partial q_y}{\partial y} + \frac{\partial}{\partial z} \left( \frac{\partial q_z}{\partial z} \right) + Q = \rho c \frac{\partial T}{\partial t}$$

## HEAT TRANSFER PROBLEM

Heat flow rates can be written in terms of temperature gradients by Fourier's law,

$$\begin{bmatrix} q_x \\ q_y \\ q_z \end{bmatrix} = - \begin{bmatrix} k_{11} & k_{12} & k_{13} \\ k_{21} & k_{22} & k_{23} \\ k_{31} & k_{32} & k_{33} \end{bmatrix} \begin{bmatrix} \frac{\partial T}{\partial x} \\ \frac{\partial T}{\partial y} \\ \frac{\partial T}{\partial z} \end{bmatrix}$$

where  $\mathbf{k}$  is the thermal conductivity matrix. As an example, for isotropic material,

$$\mathbf{k} = \begin{bmatrix} k & 0 & 0 \\ 0 & k & 0 \\ 0 & 0 & k \end{bmatrix}$$

## HEAT TRANSFER PROBLEM

### Boundary Conditions

- (1) Specified temperature on  $S_1$  :

$$T_S = T_1(x, y, z, t)$$

- (2) Specified heating on  $S_2$  :

$$q_x n_x + q_y n_y + q_z n_z = -q_S$$

- (3) Convection heat transfer on  $S_3$  :

$$q_x n_x + q_y n_y + q_z n_z = h(T_S - T_\infty)$$

## HEAT TRANSFER PROBLEM

### Boundary Conditions (Cont.)

(4) Radiation heat transfer on  $S_4$  :

$$q_x n_x + q_y n_y + q_z n_z = \epsilon \sigma (T_S^4 - T_\infty^4) + q_r$$

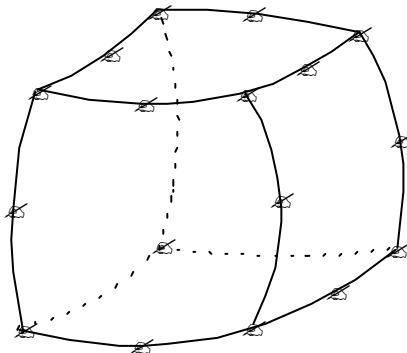
### Initial Condition

$$T(x, y, z, 0) = T_0(x, y, z)$$

## FINITE ELEMENT EQUATIONS

Assume element temperature distribution,

$$T(x, y, z, t) = \underbrace{N(x, y, z)}_{(1 \times r)} \underbrace{T(t)}_{(r \times 1)}$$



## FINITE ELEMENT EQUATIONS

Then the temperature gradients are,

$$\begin{matrix}
 \frac{\partial T}{\partial x} \\
 \frac{\partial T}{\partial y} \\
 \frac{\partial T}{\partial z}
 \end{matrix}
 \begin{matrix}
 \\
 \\
 (3 \times 1)
 \end{matrix}
 =
 \begin{matrix}
 \frac{\partial N_1}{\partial x} & \frac{\partial N_2}{\partial x} & \dots & \frac{\partial N_r}{\partial x} \\
 \frac{\partial N_1}{\partial y} & \frac{\partial N_2}{\partial y} & \dots & \frac{\partial N_r}{\partial y} \\
 \frac{\partial N_1}{\partial z} & \frac{\partial N_2}{\partial z} & \dots & \frac{\partial N_r}{\partial z}
 \end{matrix}
 \begin{matrix}
 \\
 \\
 \\
 (r \times 1)
 \end{matrix}
 \begin{matrix}
 T(t) \\
 \\
 \\
 \end{matrix}$$

$\mathbf{B}(x, y, z)$   
 (3xr)

where  $\mathbf{B}(x, y, z)$  is the temperature gradient interpolation matrix.

## FINITE ELEMENT EQUATIONS

Apply the Method of Weighted Residuals (MWR) with Bubnov-Galerkin technique,

$$\frac{\partial q_x}{\partial x} + \frac{\partial q_y}{\partial y} + \frac{\partial q_z}{\partial z} - Q + c \frac{\partial T}{\partial t} N_i = 0$$

Expand,

$$\frac{\partial q_x}{\partial x} + \frac{\partial q_y}{\partial y} + \frac{\partial q_z}{\partial z} N_i - Q N_i + c \frac{\partial T}{\partial t} N_i = 0$$

## FINITE ELEMENT EQUATIONS

Perform integration by parts using Gauss's theorem to get,

$$\int_{(e)} (\hat{q} \cdot \hat{n}) N_i d\Omega - \int_{(e)} \left( \frac{\partial N_i}{\partial x} \hat{q}_x + \frac{\partial N_i}{\partial y} \hat{q}_y + \frac{\partial N_i}{\partial z} \hat{q}_z \right) d\Omega - \int_{(e)} Q N_i d\Omega + \int_{(e)} c \frac{\partial T}{\partial t} N_i d\Omega = 0$$

Then use the Fourier's law to yield,

## FINITE ELEMENT EQUATIONS

$$\int_{(e)} (\hat{q} \cdot \hat{n}) N_i d\Omega - \int_{(e)} \mathbf{B}^T \mathbf{k} \mathbf{B} d\Omega \hat{T} - \int_{(e)} Q N_i d\Omega + \int_{(e)} c \mathbf{N}^T \mathbf{N} d\Omega \frac{\partial T}{\partial t} = 0$$

Finally, apply the boundary conditions on the boundary integral term leading to the finite element eqs. in the form,

$$\mathcal{C}^T \hat{T} + \mathbf{K}_c \hat{T} + \mathbf{K}_h \hat{T} + \mathbf{K}_r \hat{T} = \mathbf{Q}_c + \mathbf{Q}_Q + \mathbf{Q}_q + \mathbf{Q}_h + \mathbf{Q}_r$$

### FINITE ELEMENT MATRICES

$$\begin{aligned} \mathcal{C}^T &= \mathcal{K}_c + \mathcal{K}_h + \mathcal{K}_r \\ &= \mathcal{Q}_c + \mathcal{Q}_Q + \mathcal{Q}_q + \mathcal{Q}_h + \mathcal{Q}_r \end{aligned}$$

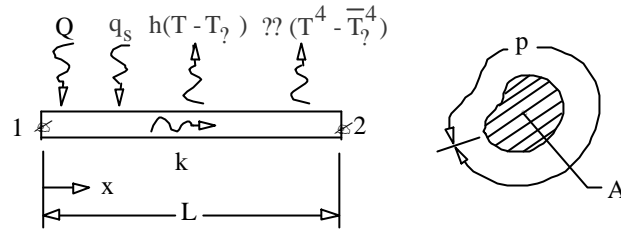
where

$$\begin{aligned} \mathcal{C} &= \int_{\Omega^{(e)}} c \mathbf{N}^T \mathbf{N} \, d\Omega \\ \mathcal{K}_c &= \int_{\Omega^{(e)}} \mathbf{B}^T \mathbf{k} \mathbf{B} \, d\Omega \\ \mathcal{K}_h &= \int_{S_3} h \mathbf{N}^T \mathbf{N} \, d\Omega \\ \mathcal{K}_r &= \int_{S_4} T^3 \mathbf{N}^T \mathbf{N} \, d\Omega \end{aligned}$$

### FINITE ELEMENT MATRICES

$$\begin{aligned} \mathcal{Q}_c &= - \int_{S_1} \hat{q} \mathbf{N}^T \, d\Omega \\ \mathcal{Q}_Q &= \int_{\Omega^{(e)}} Q \mathbf{N}^T \, d\Omega \\ \mathcal{Q}_q &= \int_{S_2} q_s \mathbf{N}^T \, d\Omega \\ \mathcal{Q}_h &= \int_{S_3} h T_\gamma \mathbf{N}^T \, d\Omega \\ \mathcal{Q}_r &= \int_{S_4} T_\gamma^4 q_r \mathbf{N}^T \, d\Omega \end{aligned}$$

### ONE-DIMENSIONAL ELEMENT



Here  $T(x, y, t) = \begin{bmatrix} N_1(x) & N_2(x) \end{bmatrix} \begin{bmatrix} T_1(t) \\ T_2(t) \end{bmatrix} = \begin{bmatrix} 1 - \frac{x}{L} & \frac{x}{L} \end{bmatrix} \begin{bmatrix} T_1(t) \\ T_2(t) \end{bmatrix}$

Then  $\frac{\partial T}{\partial x} = \begin{bmatrix} \frac{\partial N_1}{\partial x} & \frac{\partial N_2}{\partial x} \end{bmatrix} \begin{bmatrix} T_1(t) \\ T_2(t) \end{bmatrix} = \begin{bmatrix} -\frac{1}{L} & \frac{1}{L} \end{bmatrix} \begin{bmatrix} T_1(t) \\ T_2(t) \end{bmatrix}$

$B(x) \quad (1 \times 2)$

### ONE-DIMENSIONAL ELEMENT

$$C = \frac{cAL}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \quad Q_Q = \frac{QAL}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

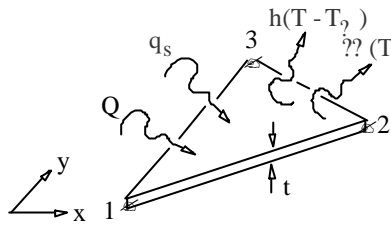
$$K_c = \frac{kA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \quad Q_q = \frac{q_s pL}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$K_h = \frac{hpL}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \quad Q_h = \frac{hT_\infty pL}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$Q_r = \begin{bmatrix} -q_r \frac{pL}{2} \\ q_r \frac{pL}{2} \end{bmatrix} \quad Q_c = \begin{bmatrix} -kA \frac{dT}{dx}(0) \\ kA \frac{dT}{dx}(L) \end{bmatrix}$$

$$K_r = \frac{pL}{60} \begin{bmatrix} 10T_1^3 & 6T_1^2T_2 & 3T_1T_2^2 & T_2^3 & 2T_1^3 & 3T_1^2T_2 & 3T_1T_2^2 & 2T_2^3 \\ 6T_1^2T_2 & 3T_1^2T_2 & 3T_1T_2^2 & 2T_2^3 & 2T_1^3 & 3T_1^2T_2 & 3T_1T_2^2 & 2T_2^3 \\ 3T_1^2T_2 & 3T_1T_2^2 & 3T_1T_2^2 & 2T_2^3 & 2T_1^3 & 3T_1^2T_2 & 6T_1T_2^2 & 10T_2^3 \end{bmatrix}$$

### TRIANGULAR ELEMENT



Element temperature,  
 $T(x, y, t) = \begin{bmatrix} N_1 & N_2 & N_3 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix}$   
 where,  $\begin{matrix} (1 \times 3) & (3 \times 1) \end{matrix}$

$$N_i = \frac{1}{2A} (a_i + b_i x + c_i y) \quad i = 1, 2, 3$$

Then the temperature gradients are,

$$\begin{bmatrix} \frac{\partial T}{\partial x} \\ \frac{\partial T}{\partial y} \end{bmatrix} = \frac{1}{2A} \begin{bmatrix} b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_3 \end{bmatrix}$$

$\mathbf{B}$   
(2x3)

### TRIANGULAR ELEMENT

$$\mathbf{C} = \frac{cAt}{12} \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix} \quad \mathbf{K}_h = \frac{hA}{12} \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$$

$$\mathbf{K}_c = \frac{kt}{4A} \begin{bmatrix} b_1 b_1 + c_1 c_1 & b_1 b_2 + c_1 c_2 & b_1 b_3 + c_1 c_3 \\ b_2 b_2 + c_2 c_2 & b_2 b_3 + c_2 c_3 \\ b_3 b_3 + c_3 c_3 \end{bmatrix} \text{ Sym}$$

$$\mathbf{Q}_Q = \frac{QAt}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}; \quad \mathbf{Q}_q = \frac{q_s A}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}; \quad \mathbf{Q}_h = \frac{hT_\infty A}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$



## TRIANGULAR ELEMENT

If there is convection heat transfer along the edge length  $\Delta$  between nodes 1 and 2, then the corresponding matrices are,

$$K_h = \frac{h t \Delta}{6} \begin{bmatrix} 2 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

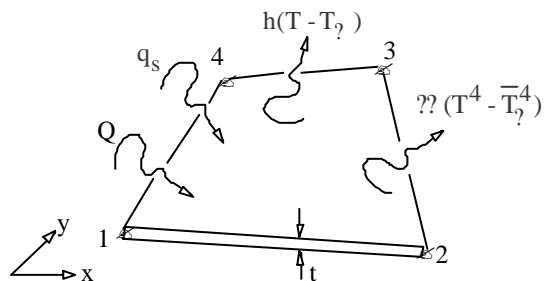
$$Q_h = \frac{h T_\infty t \Delta}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

## QUADRILATERAL ELEMENT

Element temperature,

$$T(x, y, t) = N(x, y) T(t)$$

(1x4)      (4x1)



Then the temperature gradients,

## QUADRILATERAL ELEMENT

$$\begin{matrix}
 \frac{\partial T}{\partial x} \\
 \frac{\partial T}{\partial y}
 \end{matrix}
 =
 \begin{bmatrix}
 J_{11}^* & J_{12}^* \\
 J_{21}^* & J_{22}^*
 \end{bmatrix}
 \begin{bmatrix}
 N_1 \\
 N_2 \\
 N_3 \\
 N_4
 \end{bmatrix}
 \begin{matrix}
 T_1 \\
 T_2 \\
 T_3 \\
 T_4
 \end{matrix}$$

$\mathcal{B}(?,?)$   
 (2x4)

where  $J_{ij}^*$ ,  $i, j = 1, 2$  are the coefficients in the inverse Jacobian matrix.

## QUADRILATERAL ELEMENT

Finite element matrices,

$$\begin{aligned}
 \mathcal{C} &= \int_{-1}^1 \int_{-1}^1 c N(\xi, \eta) N(\xi, \eta) t |J| d\xi d\eta \\
 \mathcal{K}_c &= \int_{-1}^1 \int_{-1}^1 \mathcal{B}(\xi, \eta)^T k \mathcal{B}(\xi, \eta) t |J| d\xi d\eta \\
 \mathcal{K}_h &= \int_{-1}^1 \int_{-1}^1 h N(\xi, \eta) N(\xi, \eta) |J| d\xi d\eta \\
 \mathcal{Q}_Q &= \int_{-1}^1 \int_{-1}^1 Q N(\xi, \eta) t |J| d\xi d\eta \\
 \mathcal{Q}_q &= \int_{-1}^1 \int_{-1}^1 q_s N(\xi, \eta) |J| d\xi d\eta \\
 \mathcal{Q}_h &= \int_{-1}^1 \int_{-1}^1 h T_\gamma N(\xi, \eta) |J| d\xi d\eta
 \end{aligned}$$

## QUADRILATERAL ELEMENT

These element matrices are evaluated using Gauss-Legendre numerical integration. For examples,

$$C = \int_{-1}^1 \int_{-1}^1 c N(\xi, \eta) N(\xi, \eta) t |J| d\xi d\eta$$

$$= \sum_{i=1}^{NG} \sum_{j=1}^{NG} W_i W_j c N(\xi_i, \eta_j) N(\xi_i, \eta_j) t |J(\xi_i, \eta_j)|$$

## QUADRILATERAL ELEMENT

and

$$K_c = \int_{-1}^1 \int_{-1}^1 B(\xi, \eta)^T k B(\xi, \eta) t |J| d\xi d\eta$$

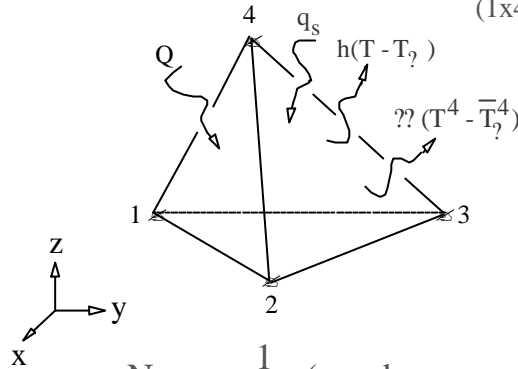
$$= \sum_{i=1}^{NG} \sum_{j=1}^{NG} W_i W_j B(\xi_i, \eta_j)^T k B(\xi_i, \eta_j) t |J(\xi_i, \eta_j)|$$

where  $W_i, W_j$  are the weights;  $\xi_i, \eta_j$  are the Gauss point locations for the total of NG points.

### TETRAHEDRAL ELEMENT

Element temperature,

$$T(x, y, z, t) = \begin{matrix} \boxed{N} & \boxed{x, y, z} & \boxed{T(t)} \\ (1 \times 4) & & (4 \times 1) \end{matrix}$$



where the interpolation functions,

$$N_i = \frac{1}{6A} (a_i + b_i x + c_i y + d_i z) \quad i = 1, 2, 3, 4$$

### TETRAHEDRAL ELEMENT

Then the element temperature gradients are,

$$\begin{matrix} \frac{\partial T}{\partial x} \\ \frac{\partial T}{\partial y} \\ \frac{\partial T}{\partial z} \end{matrix} = \frac{1}{6V} \begin{matrix} b_1 & b_2 & b_3 & b_4 \\ c_1 & c_2 & c_3 & c_4 \\ d_1 & d_2 & d_3 & d_4 \end{matrix} \begin{matrix} T(t) \\ \\ \\ \end{matrix} \begin{matrix} (4 \times 1) \\ \\ \\ \end{matrix}$$

$\mathbf{B}$   
(3x4)

## TETRAHEDRAL ELEMENT

Element matrices can be derived in closed form.  
For examples,

$$[C] = \frac{cV}{20} \begin{bmatrix} 2 & 1 & 1 & 1 \\ 1 & 2 & 1 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 1 & 1 & 2 \end{bmatrix}; \quad [Q_Q] = \frac{QV}{4} \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$K_{c_{ij}} = \frac{1}{36V} (b_i b_j + c_i c_j + d_i d_j) \quad i, j = 1, 2, 3, 4$$

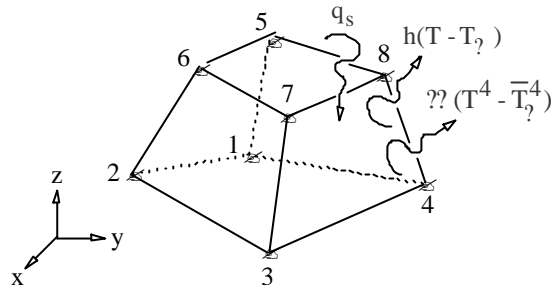
## TETRAHEDRAL ELEMENT

If there is convection heat transfer on the element face connecting nodes 2-3-4, then the corresponding matrices are,

$$[K_h] = \frac{hA}{12} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 2 & 1 & 1 \\ 0 & 1 & 2 & 1 \\ 0 & 1 & 1 & 2 \end{bmatrix}; \quad [Q_h] = \frac{hT_\infty A}{3} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

where A is the area of that face.

### HEXAHERAL ELEMENT



Element temperature distribution,

$$T(x, y, z, t) = \sum_{i=1}^8 N_i(x, y, z) T_i(t)$$

(1x8)                      (8x1)

where  $N_i(x, y, z)$ ,  $i = 1, 8$  are the element interpolation functions.

### HEXAHERAL ELEMENT

The element temperature gradient can be derived,

$$\begin{bmatrix} \frac{\partial T}{\partial x} \\ \frac{\partial T}{\partial y} \\ \frac{\partial T}{\partial z} \end{bmatrix} = \begin{bmatrix} J_{11}^2 & J_{12}^2 & J_{13}^2 \\ J_{21}^2 & J_{22}^2 & J_{23}^2 \\ J_{31}^2 & J_{32}^2 & J_{33}^2 \end{bmatrix} \begin{bmatrix} \frac{\partial N_1}{\partial x} & \frac{\partial N_2}{\partial x} \\ \frac{\partial N_1}{\partial y} & \frac{\partial N_2}{\partial y} \\ \frac{\partial N_1}{\partial z} & \frac{\partial N_2}{\partial z} \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \\ T_8 \end{bmatrix}$$

$$= \mathbf{B}(x, y, z) \mathbf{T}(t)$$

(3x8)                      (8x1)

where  $J_{ij}^2$ ,  $i, j = 1, 2, 3$  are the coefficients in the inverse Jacobian matrix and  $\mathbf{B}(x, y, z)$  is the temperature gradient interpolation matrix needed in the derivation of the conduction matrix.

## HEXAHEDRAL ELEMENT

Then finite element matrices can be derived in integral form. Typical element matrices, such as the capacitance and conduction matrices, including load vector from heat generation are,

$$C = \int_{-1}^1 \int_{-1}^1 \int_{-1}^1 c N(x,y,z) N(x,y,z) |J| dx dy dz$$

$$K_c = \int_{-1}^1 \int_{-1}^1 \int_{-1}^1 B(x,y,z)^T k B(x,y,z) |J| dx dy dz$$

$$Q_Q = \int_{-1}^1 \int_{-1}^1 \int_{-1}^1 Q N(x,y,z) |J| dx dy dz$$

## HEXAHEDRAL ELEMENT

These element matrices are evaluated using Gauss-Legendre numerical integration as,

$$C = \sum_{i=1}^{NG} \sum_{j=1}^{NG} \sum_{k=1}^{NG} W_i W_j W_k c N(x_i, y_j, z_k) N(x_i, y_j, z_k) |J(x_i, y_j, z_k)|$$

$$K_c = \sum_{i=1}^{NG} \sum_{j=1}^{NG} \sum_{k=1}^{NG} W_i W_j W_k B(x_i, y_j, z_k)^T k B(x_i, y_j, z_k) |J(x_i, y_j, z_k)|$$

$$Q_Q = \sum_{i=1}^{NG} \sum_{j=1}^{NG} \sum_{k=1}^{NG} W_i W_j W_k Q N(x_i, y_j, z_k) |J(x_i, y_j, z_k)|$$

where  $W_i, W_j, W_k$  are the weights;  $x_i, y_j, z_k$  are the Gauss point locations for the total of  $NG$  points.

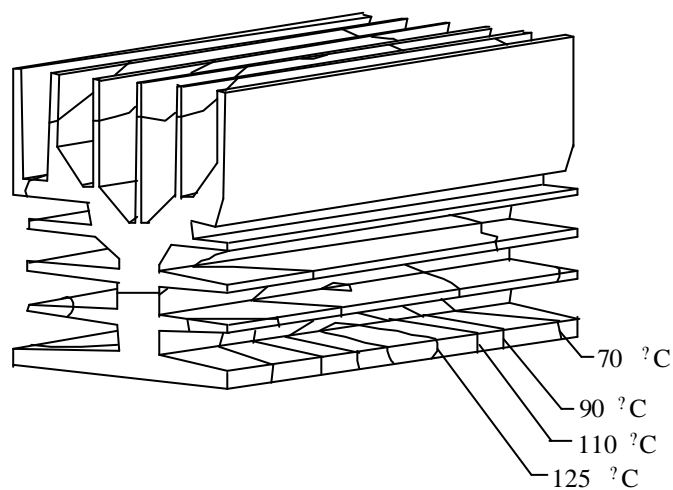
## LINEAR STEADY-STATE HEAT TRANSFER

For linear steady-state heat transfer problems, the derived finite element equations reduce to,

$$[K_c] + [K_h] T = Q_c + Q_Q + Q_q + Q_h$$

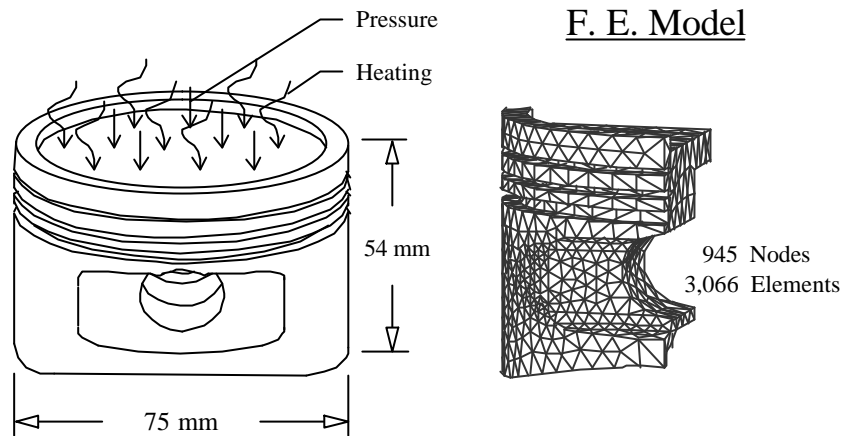
Solving such problems poses no difficulty. The system of algebraic eqs. can be solved conveniently using standard methods such as Gauss elimination, LU decomposition, etc.

## AMPLIFIER FIN TEMPERATURE

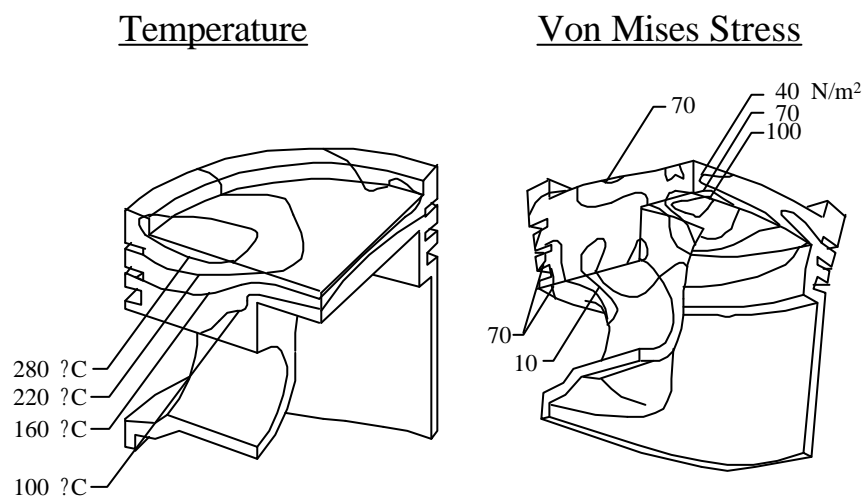




## MOTORCYCLE PISTON



## MOTORCYCLE PISTON



## LINEAR TRANSIENT HEAT TRANSFER

Finite element equations:

$$[C] \frac{dT}{dt} + [K_c] + [K_h] T = Q_c + Q_Q + Q_q + Q_h$$

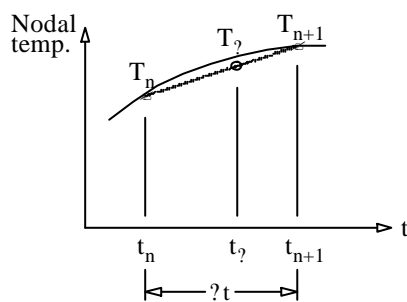
The square matrices on LHS are not function of temperature and the load vectors on RHS may depend on time. These element eqs. can be written, in short, as

$$[C] \frac{dT}{dt} + [K] T = Q$$

where  $[K] = [K_c] + [K_h]$

$$Q = Q_c + Q_Q + Q_q + Q_h$$

## RECURRENCE RELATIONS



Knowing temperature  $T_n$  at time  $t_n$ , want to compute temperature  $T_{n+1}$  at time  $t_{n+1}$  using the time step of  $\Delta t$ .

From the figure,

$$t_\gamma = t_n + \theta \Delta t \quad 0 \leq \theta \leq 1$$

and the approximate temperature gradient is,

$$\frac{dT}{dt} \approx \frac{T_{n+1} - T_n}{\Delta t}$$

Then, the temperature at time  $t_\gamma$  is,

$$T_\gamma \approx (1 - \theta) T_n + \theta T_{n+1}$$

## RECURRENCE RELATIONS

Finite element equations are evaluated at time  $t_n$ ,

$$C \dot{T}_n + K T_n = Q_n$$

Since the nodal temperature gradients are,

$$\dot{T}_n = \frac{T_{n+1} - T_n}{\Delta t}$$

and the nodal temperatures,

$$T_n = (1 - \theta) T_n + \theta T_{n+1}$$

Also the load vector at time  $t_n$ ,

$$Q_n = (1 - \theta) Q_n + \theta Q_{n+1}$$

Substitute these into the FE eqs. above to yield,

## RECURRENCE RELATIONS

$$\frac{1}{\Delta t} C \dot{T}_{n+1} + K T_{n+1} = \frac{1}{\Delta t} C \theta (T_{n+1} - T_n) - (1 - \theta) K T_n + (1 - \theta) Q_n + \theta Q_{n+1}$$

Solution procedure and results depend on  $\theta$  selected,

$\theta$	Method
0	Euler
1/2	Crank-Nicolson
2/3	Galerkin
1	Backward difference

## EULER METHOD

If  $\Delta t \neq 0$ , the element equations reduce to,

$$\frac{1}{\Delta t} \mathcal{C} T_{n+1} = \frac{1}{\Delta t} \mathcal{C} T_n - \mathcal{K} T_n + Q_n$$

In addition, if  $[C]$  is lumped, then can solve “Uncoupled equations”. As an example, the capacitance matrix for 1-D rod element is,

$$\mathcal{C} = cAL \begin{bmatrix} \frac{1}{3} & \frac{1}{6} \\ \frac{1}{6} & \frac{1}{3} \end{bmatrix}$$

## EULER METHOD

The corresponding lumped capacitance matrix is,

$$\mathcal{C}_{\text{lumped}} = cAL \begin{bmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{bmatrix}$$

For other element types, the coefficients along the diagonal line of the lumped capacitance matrix are determined from,

$$C_{ii} = \int_{(e)} c N_i^2 dx$$

## EULER METHOD

Note that the Euler method,

- ∞ leads to uncoupled eqs. called “Explicit method”, that helps saving computer memory.
- ∞ the time step used must be less than the critical time step, if not, the solution can diverge.

## CRANK-NICOLSON METHOD

If  $\theta=1/2$ , the element equations become,

$$\frac{1}{2} \frac{C}{t} T_{n+1} - \frac{1}{2} K T_n = \frac{1}{2} \frac{C}{t} T_n - \frac{1}{2} K T_n + \frac{1}{2} Q_n + \frac{1}{2} Q_{n+1}$$

which are coupled equations. The method is called “Implicit method” that,

- ∞ can use larger time step than the Euler method
- ∞ can provide higher solution accuracy
- ∞ may give oscillation of solution if time step is too high

## GALERKIN & BACKWARD DIFFERENCE METHODS

$$\frac{1}{\Delta t} [C - \frac{1}{2}K] T_{n+1} = \frac{1}{\Delta t} [C - (1 - \frac{1}{2})K] T_n + (1 - \frac{1}{2})Q_n + \frac{1}{2}Q_{n+1}$$

Galerkin method ( $\alpha = 2/3$ )

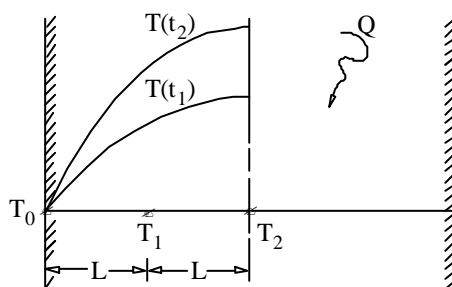
- ⌘ If use large time step, oscillation is less than Crank-Nicolson
- ⌘ However, solution accuracy is also reduced

Backward difference method ( $\alpha = 1$ )

- ⌘ Provides smooth solution with no oscillation
- ⌘ Gives less solution accuracy compared to other methods

## TRANSIENT HEAT CONDUCTION IN SLAB

Governing diff. eq.:  $\rho c \frac{\partial T}{\partial t} - k \frac{\partial^2 T}{\partial x^2} = Q$



Boundary conditions,

$$T(0,t) = T(L,t) = 0$$

Initial condition

$$T(x,0) = 0 \quad \text{and}$$

$$Q(x,t) = \begin{cases} 0 & t < 0 \\ Q_0 & t \geq 0 \end{cases}$$

Use 2 elements to compute transient nodal temperatures  $T_1(t)$  and  $T_2(t)$  in the figure.

## TRANSIENT HEAT CONDUCTION IN SLAB

Finite element eqs. for this problem are,

$$[C] \{T\} + [K_c] \{T\} = \{Q_c\} + \{Q_Q\}$$

and the typical element eqs. are,

$$\begin{aligned}
 \frac{1}{6} cAL \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} + \frac{kA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} \\
 = \begin{bmatrix} -kA \frac{dT}{dx}(0) \\ kA \frac{dT}{dx}(L) \end{bmatrix} + \frac{Q_0 AL}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}
 \end{aligned}$$

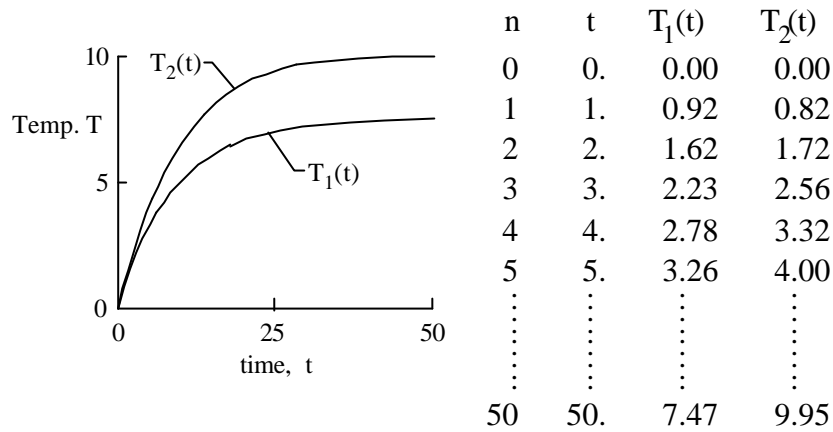
## TRANSIENT HEAT CONDUCTION IN SLAB

Given  $L = 1/4$ ,  $\rho = 4$ ,  $c = 3$ ,  $k = 1/8$  and  $Q_0 = 10$  element eqs. are assembled. After applying boundary conditions, the system eqs. reduce to,

$$\begin{bmatrix} 2 & 0.5 \\ 0.5 & 1 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} + \begin{bmatrix} 1 & -0.5 \\ -0.5 & 0.5 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} = \begin{bmatrix} 2.50 \\ 1.25 \end{bmatrix}$$

### TRANSIENT HEAT CONDUCTION IN SLAB

Then applying the Crank-Nicolson method with  $\Delta t = 1$ , this leads to the solution below,



### TRANSIENT HEAT CONDUCTION IN SLAB

If use the Euler method, the system eqs. are uncoupled,

$$\begin{bmatrix} 1 & 0 \\ 0 & 1.5 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} + \begin{bmatrix} -1 & 0 \\ 0 & -0.5 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} = \begin{bmatrix} 2.50 \\ 1.25 \end{bmatrix}$$

n	t	Euler		Crank-Nicolson	
		T <sub>1</sub> (t)	T <sub>2</sub> (t)	T <sub>1</sub> (t)	T <sub>2</sub> (t)
0	0.	0.00	0.00	0.00	0.00
1	1.	0.83	0.83	0.92	0.82
2	2.	1.53	1.67	1.62	1.72
3	3.	2.13	2.45	2.23	2.56
4	4.	2.66	3.18	2.78	3.32
5	5.	3.14	3.84	3.26	4.00
⋮	⋮	⋮	⋮	⋮	⋮
50	50.	7.46	9.94	7.47	9.95



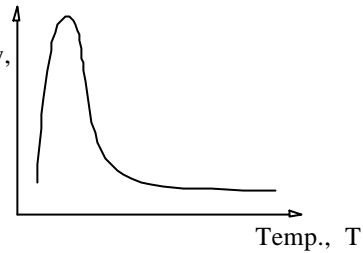
## NONLINEAR STEADY-STATE HEAT TRANSFER

Finite element equations:

$$[K_c(T)] + [K_h(T)] + [K_r(T)] T = Q$$

As an example, the conduction matrix

Thermal conductivity,  $k(T)$

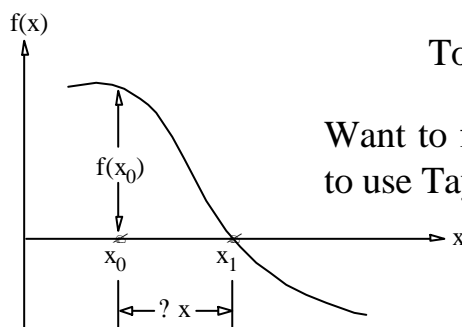


$$[K_c] = \int [B]^T k(T) [B] dV$$

The above element eqs. can be written, in short, as:

$$[K(T)] T = Q$$

## NEWTON-RAPHSON ITERATION TECHNIQUE



To solve,  $f(x) = 0$

Want to find the root  $x_1$ . Idea is to use Taylor series expansion,

$$f(x_1) = f(x_0 + \Delta x) = f(x_0) + \left. \frac{df}{dx} \right|_{x_0} \Delta x + \dots = 0$$

## NEWTON-RAPHSON ITERATION TECHNIQUE

Compute  $\Delta x$  by taking only the first two terms,

$$\left. \frac{df}{dx} \right|_{x_0} \Delta x = -f(x_0)$$

$$J(x^0)$$

Then the approximate  $x_1$  is,

$$x_1 = x_0 + \Delta x$$

## NEWTON-RAPHSON ITERATION TECHNIQUE

In conclusion, the iteration procedure is,

1. Solve  $J(x^m) \Delta x^{m+1} = -f(x^m)$   
where  $J(x^m)$  is the Jacobian at the  $m^{\text{th}}$  iteration
2. Update  $x^{m+1} = x^m + \Delta x^{m+1}$
3. Check for convergence. If yes  $\Rightarrow$  Stop  
No  $\Rightarrow$  Go to step 1

## NEWTON-RAPHSON ITERATION TECHNIQUE

Now, for a set of  $n$  simultaneous finite element eqs., start from guessing a set of nodal temperature solutions,

$$\mathbf{K}(\mathbf{T})\mathbf{T} - \mathbf{Q} = \mathbf{0} \quad \text{but} \quad = \mathbf{R}$$

where  $\mathbf{R}$  is the residual vector. The residual for the  $i^{\text{th}}$  eq. is

$$R_i = \sum_{j=1}^n K_{ij}(T_1, T_2, \dots, T_n) T_j - Q_i$$

## NEWTON-RAPHSON ITERATION TECHNIQUE

Similarly, apply Taylor series expansion,

$$\begin{aligned} R_i(T_1 + \delta T_1, T_2 + \delta T_2, \dots, T_n + \delta T_n) \\ = R_i(T_1, T_2, \dots, T_n) + \sum_{j=1}^n \frac{\partial R_i}{\partial T_j}(T_1, T_2, \dots, T_n) \delta T_j + \dots \\ = 0 \end{aligned}$$

and take only the first two terms to get,

$$\sum_{j=1}^n \frac{\partial R_i}{\partial T_j}(T_1, T_2, \dots, T_n) \delta T_j = -R_i(T_1, T_2, \dots, T_n)$$

## NEWTON-RAPHSON ITERATION TECHNIQUE

which can be written in matrix form as,

$$\begin{matrix}
 \frac{R_1}{T_1} & \frac{R_1}{T_2} & \dots & \frac{R_1}{T_n} \\
 \frac{R_2}{T_1} & \frac{R_2}{T_2} & \dots & \frac{R_2}{T_n} \\
 \vdots & \vdots & \ddots & \vdots \\
 \frac{R_n}{T_1} & \frac{R_n}{T_2} & \dots & \frac{R_n}{T_n}
 \end{matrix}
 \begin{matrix}
 \square & \square & & \\
 \square & \square & & \\
 & & \square & \square \\
 & & & \square & \square
 \end{matrix}
 \begin{matrix}
 \frac{R_1}{T_1} \\
 \frac{R_2}{T_2} \\
 \vdots \\
 \frac{R_n}{T_n}
 \end{matrix}
 = -
 \begin{matrix}
 R_1 \\
 R_2 \\
 \vdots \\
 R_n
 \end{matrix}
 \begin{matrix}
 T_1 \\
 T_2 \\
 \vdots \\
 T_n
 \end{matrix}$$

$(n \times n)$                        $(n \times 1)$                        $(n \times 1)$

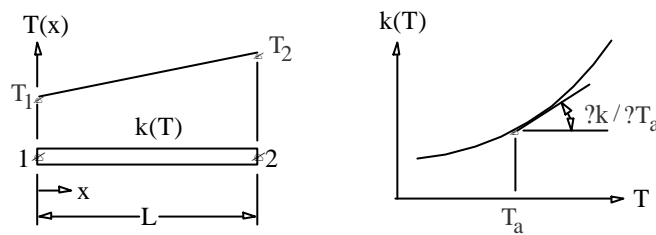
## NEWTON-RAPHSON ITERATION TECHNIQUE

Thus the iteration procedure is,

1. Solve  $J(T)^m T^{m+1} = -R^m$   
where  $m$  is the  $m^{\text{th}}$  iteration.
2. Update  $T^{m+1} = T^m + T^{m+1}$   
and check for convergence.

## TEMPERATURE DEPENDENT MATERIAL PROPERTIES

Example Derive the Jacobian matrix for rod element with temperature dependent thermal conductivity.



\_\_\_\_\_ Here, the element eqs. are,  $\{K(T)\}T = \{Q\}$

Then the residuals vector is,  $\{R\} = \{K(T)\}T - \{Q\}$

## TEMPERATURE DEPENDENT THERMAL CONDUCTIVITY

Since the coefficients in the Jacobian matrix are,

$$\begin{aligned}
 J_{ij} &= \frac{\partial R_i}{\partial T_j} = \frac{\partial}{\partial T_j} \sum_{\square=1}^2 (K_{i\square} T_{\square} - Q_i) \\
 &= \sum_{\square=1}^2 K_{i\square} \frac{\partial T_{\square}}{\partial T_j} + \sum_{\square=1}^2 \frac{\partial K_{i\square}}{\partial T_j} T_{\square} - 0 \\
 J_{ij} &= K_{ij} + \sum_{\square=1}^2 \frac{\partial K_{i\square}}{\partial T_j} T_{\square}
 \end{aligned}$$

## TEMPERATURE DEPENDENT THERMAL CONDUCTIVITY

Since the average temperature is  $T_a = (T_1 + T_2)/2$ , then,

$$\begin{aligned} J_{ij} &= K_{ij} \left[ \frac{2}{L} \frac{\partial K_{ij}}{\partial T_a} \frac{T_a}{T_j} T_{ij} \right] \\ &= K_{ij} \left[ \frac{1}{2} \frac{\partial K_{ij}}{\partial T_a} \right] T_{ij} \end{aligned}$$

## TEMPERATURE DEPENDENT THERMAL CONDUCTIVITY

Thus, the Jacobian matrix is,

$$J = \frac{kA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + \frac{1}{2} \frac{\partial k}{\partial T_a} \frac{A}{L} \begin{bmatrix} T_1 - T_2 & T_1 - T_2 \\ T_1 + T_2 & -T_1 + T_2 \end{bmatrix}$$

which can be used for programming directly. Note that  $\partial k / \partial T_a$  is the slope of thermal conductivity wrt. temperature at the average element temperature. Such quantity can be computed from user input table. Also note that [J] is unsymmetric matrix, thus more memory is required in addition to more CPU time from iteration procedure.

## NONLINEARITY FROM RADIATION

Finite element equations are,

$$[K_c] + [K_r(T)] T = \{Q_c\} + \{Q_r\}$$

From a set of guessing nodal temperatures, the residual vector is,

$$\{R\} = [K_c] T + \sum_{S=1}^S \sigma T^4 N_d - \{Q_c\} - \{Q_r\}$$

$\{R\}_{cond} \quad \{R\}_{rad} \quad \{R\}_{load}$

## NONLINEARITY FROM RADIATION

Applying the Newton-Raphson iteration method,

$$[J]^m T^{m+1} = -\{R\}^m$$

Here the coefficients in the Jacobian matrix are,

$$J_{ij} = (J_{ij})_{cond} + (J_{ij})_{rad} + (J_{ij})_{load}$$

$$= \frac{\partial R_i}{\partial T_j}_{cond} + \frac{\partial R_i}{\partial T_j}_{rad} + \frac{\partial R_i}{\partial T_j}_{load}$$

## RADIATION HEAT TRANSFER

For independent material thermal conductivity,

$$(J_{ij})_{\text{cond}} = K_{c_{ij}} \quad \text{or} \quad \frac{\partial J}{\partial T_j} = \frac{\partial K_c}{\partial T_j}$$

The Jacobian matrix coefficients from radiation can be derived,

$$\begin{aligned} (J_{ij})_{\text{rad}} &= \frac{\partial}{\partial T_j} \left( \frac{\sigma T_i^4 N_i d}{s_4} \right) \\ &= \frac{\partial}{\partial T_j} \left( \sigma (4T_i^3 \frac{\partial T_i}{\partial T_j}) N_i d \right) \end{aligned}$$

But  $\frac{\partial T_i}{\partial T_j} = \frac{\partial}{\partial T_j} (N_i T_i) = N_i \frac{\partial T_i}{\partial T_j} = N_j$

## RADIATION HEAT TRANSFER

Then  $(J_{ij})_{\text{rad}} = \frac{\sigma 4 T_i^3 N_i N_j d}{s_4} \quad \text{or}$

$$\frac{\partial J}{\partial T_j} = \frac{\sigma 4 T_i^3 N_i N_j d}{s_4}$$

Thus, the finite element eqs. needed for solution are,

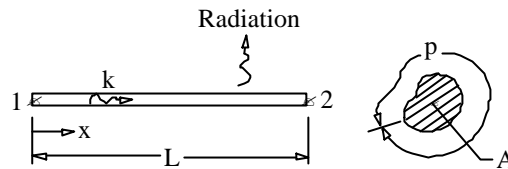
$$\frac{\partial J}{\partial T_j} \frac{\partial T_j}{\partial T} = -R_{\text{cond}}^m - R_{\text{rad}}^m - R_{\text{load}}^m$$

where  $m$  is the  $m^{\text{th}}$  iteration.



## RADIATION HEAT TRANSFER

Example Derive the Jacobian matrices and residual vectors for rod element with surface radiation.



$$\text{Here } T(x) = \begin{bmatrix} N_1 & N_2 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} = \begin{bmatrix} 1 - \frac{x}{L} & \frac{x}{L} \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix}$$

Then

$$\mathbf{J}_{\text{cond}} = \mathbf{K}_c = \int_0^L \begin{bmatrix} N_1 \\ N_2 \end{bmatrix} k \begin{bmatrix} N_1 & N_2 \end{bmatrix} (A dx) = \frac{kA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

## ROD WITH SURFACE RADIATION

$$\begin{aligned} \mathbf{J}_{\text{rad}} &= \int_0^L 4 \epsilon (N_1 T_1 + N_2 T_2)^3 \begin{bmatrix} N_1 \\ N_2 \end{bmatrix} \begin{bmatrix} N_1 & N_2 \end{bmatrix} (p dx) \\ &= \frac{4 \epsilon p L}{15} \begin{bmatrix} 10 T_1^3 & 6 T_1^2 T_2 & 3 T_1 T_2^2 & T_2^3 & 2 T_1^3 & 3 T_1^2 T_2 & 3 T_1 T_2^2 & 2 T_2^3 \\ 3 T_1^2 & 3 T_1 T_2 & 3 T_1 T_2^2 & 2 T_2^3 & T_1^3 & 3 T_1^2 T_2 & 6 T_1 T_2^2 & 10 T_2^3 \end{bmatrix} \end{aligned}$$

$$\mathbf{R}_{\text{cond}} = \mathbf{K}_c \mathbf{T} = \frac{kA}{L} \begin{bmatrix} T_1 - T_2 \\ -T_1 + T_2 \end{bmatrix}$$

$$\begin{aligned} \mathbf{R}_{\text{rad}} &= \int_0^L \epsilon (N_1 T_1 + N_2 T_2)^4 \begin{bmatrix} N_1 \\ N_2 \end{bmatrix} (p dx) \\ &= \frac{4 \epsilon p L}{30} \begin{bmatrix} 5 T_1^4 & 4 T_1^3 T_2 & 3 T_1^2 T_2^2 & 2 T_1 T_2^3 & T_2^4 \\ 3 T_1^4 & 2 T_1^3 T_2 & 3 T_1^2 T_2^2 & 4 T_1 T_2^3 & 5 T_2^4 \end{bmatrix} \end{aligned}$$

## NONLINEAR TRANSIENT HEAT TRANSFER

\_\_\_\_\_ Finite element equations,

$$[C(T)] \dot{T}(t) + [K(T)] T(t) = Q(T, t)$$

Example Derive the Jacobian and the residual for a single DOF nonlinear transient equation,

$$\dot{T} + (a + bT) T = 0$$

where  $a$  and  $b$  are constants. The initial condition is  $T(t=0) = T_0$ .

## NONLINEAR TRANSIENT HEAT TRANSFER

\_\_\_\_\_ To solve this problem, we need to apply the recurrence relations. and then the Newton-Raphson iteration. By comparing the given diff. eq. and the FE eqs., we have,

$$[C(T)] = 1, \quad [K(T)] = a + bT, \quad Q(T, t) = 0$$

As an example, applying Crank-Nicolson ( $\theta = 1/2$ ) leads to,

$$\frac{1}{\Delta t} \left[ \frac{1}{2} (a + bT_{n+1/2}) \right] T_{n+1} = \frac{1}{\Delta t} \left[ \frac{1}{2} (a + bT_{n+1/2}) \right] T_n$$

where  $n$  is the  $n^{\text{th}}$  time step.

## NONLINEAR TRANSIENT HEAT TRANSFER

Since  $T_{n+1/2} = \frac{1}{2}(T_n + T_{n+1})$ , then,

$$\begin{aligned} \frac{\rho V c_p}{4} \frac{dT_{n+1}}{dt} + a \frac{A}{2} (T_n - T_{n+1}) &= b \frac{A}{4} T_n - b \frac{A}{4} T_{n+1} \\ &= \frac{\rho V c_p}{4} \frac{dT_n}{dt} - a \frac{A}{2} T_n - b \frac{A}{4} T_n + b \frac{A}{4} T_{n+1} \end{aligned}$$

which is in form of nonlinear equation,

$$\bar{K}(T_{n+1}) T_{n+1} = \bar{Q}(T_{n+1})$$

## NONLINEAR TRANSIENT HEAT TRANSFER

Then applying the Newton-Raphson iteration method. The residual,

$$R = \bar{K}(T_{n+1}) T_{n+1} - \bar{Q}(T_{n+1})$$

which leads to the incremental equation,

$$J^m \Delta T_{n+1}^m = -R^m$$

where  $m$  is the  $m^{\text{th}}$  iteration. Here,

$$\begin{aligned} R^m &= \frac{\rho V c_p}{4} \frac{dT_{n+1}^m}{dt} + a \frac{A}{2} (T_n - T_{n+1}^m) - b \frac{A}{4} T_n + b \frac{A}{4} T_{n+1}^m \\ &\quad - \left[ \frac{\rho V c_p}{4} \frac{dT_n}{dt} - a \frac{A}{2} T_n - b \frac{A}{4} T_n + b \frac{A}{4} T_{n+1}^m \right] \end{aligned}$$

## NONLINEAR TRANSIENT HEAT TRANSFER

Then the Jacobian is,

$$\begin{aligned} J^m &= \frac{\partial R^m}{\partial T_n^m} \\ &= 1 + a \frac{\partial t}{2} + b \frac{\partial t}{4} T_n + b \frac{\partial t}{4} T_{n+1}^m \end{aligned}$$

In conclusion, at each time step, need to perform iteration and solve the incremental equation. The iteration process is repeated for the total number of time steps specified.

## CONVECTIVE-DIFFUSION EQUATION

Governing differential equation,

$$\begin{aligned} - \left( \frac{\partial q_x}{\partial x} + \frac{\partial q_y}{\partial y} + \frac{\partial q_z}{\partial z} \right) - \rho c (u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial y} + w \frac{\partial T}{\partial z}) + Q \\ = \rho c \frac{\partial T}{\partial t} \end{aligned}$$

where  $u, v, w$  are the given velocity components in the  $x, y, z$  directions, respectively. Using MWR, the corresponding FE eqs. can be derived as,

## CONVECTIVE-DIFFUSION EQUATION

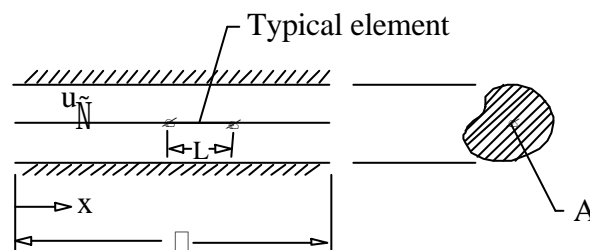
$$\begin{aligned}
 [C] \{T\} + [K_c] + [K_h] + [K_v] \{T\} \\
 = \{Q_c\} + \{Q_Q\} + \{Q_q\} + \{Q_h\}
 \end{aligned}$$

All matrices are the same as before, except the new matrix,

$$[K_v] = \frac{\rho c N u}{\Delta x} [B]^T [B]$$

which is called “the mass transport convection matrix”.

## ONE-DIMENSIONAL STEADY-STATE CONVECTIVE-DIFFUSION EQUATION



Governing differential equation,

$$kA \frac{d^2 T}{dx^2} - \rho c A u \frac{dT}{dx} = 0$$

## ONE-DIMENSIONAL STEADY-STATE CONVECTIVE-DIFFUSION EQUATION

and the corresponding finite element eqs. are,

$$\{K_c\} + \{K_v\}\{T\} = \{Q_c\}$$

If use standard linear element,

$$\begin{aligned} T(x) &= \{N_1 \quad N_2\} \begin{Bmatrix} T_1 \\ T_2 \end{Bmatrix} \\ &= \left[ 1 - \frac{x}{L} \quad \frac{x}{L} \right] \begin{Bmatrix} T_1 \\ T_2 \end{Bmatrix} \end{aligned}$$

## FINITE ELEMENT MATRICES

Then the conduction matrix and conduction vector are,

$$\{K_c\} = \int_0^L \{B\}^T k \{B\} (A dx) = \frac{kA}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

$$\{Q_c\} = \left( \{N\}^T kA \frac{dT}{dx} \right) \Big|_0^L = \begin{bmatrix} -kA \frac{dT}{dx}(0) \\ kA \frac{dT}{dx}(L) \end{bmatrix}$$

and the mass transport convection matrix (Bubnov-Galerkin) is,

$$\{K_v\} = \int_0^L \{c\} \{N\}^T u \{B\} (A dx) = \frac{cAu}{2} \begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix}$$

## FINITE ELEMENT MATRICES

Then the finite element eqs. are,

$$\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} + \frac{Pe}{2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} T_1 \\ T_2 \end{bmatrix} = \begin{bmatrix} -L \frac{dT}{dx}(0) \\ L \frac{dT}{dx}(L) \end{bmatrix}$$

where  $Pe = \rho c u L / k$  is called "grid Peclet number" that depends on the element length.

## PETROV-GALERKIN FORMULATION

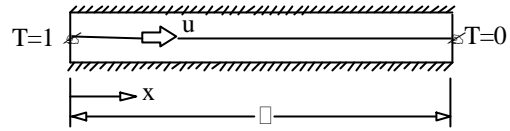
Note that solution oscillates if element length is too large. Oscillation can be eliminated by using different weighting functions,

$$\begin{bmatrix} W_1 \\ W_2 \end{bmatrix} = \begin{bmatrix} N_1 \\ N_2 \end{bmatrix} + 3 \left( \frac{x^2}{L^2} - \frac{x}{L} \right) \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

where  $\beta$  is a constant. If  $\beta=0$  then  $\{W\}=\{N\}$  which is the standard Bubnov-Galerkin formulation. If  $\beta=1$  is called full upwinding finite element that always give smooth temperature distribution. The corresponding mass transport convection matrix is,

$$K_v = \int_0^L \rho c W^T u B^T (A dx) = \frac{\rho c A u}{2} \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} + \beta \frac{\rho c A u}{2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

## CONVECTIVE-DIFFUSION EXAMPLE



Exact temperature distribution,

$$T(x) = 1 - (1 - e^{-Pe x/L}) / (1 - e^{-Pe L/L})$$

